



**ACS** College of Engineering  
Approved by AICTE New Delhi, Affiliated to VTU, Belagavi  
(A Unit of RajaRajeswari Group of Institutions)



**DEPARTMENT OF ELECTRONICS AND COMMUNICATION ENGINEERING**

**SUBJECT: BASIC SIGNAL PROCESSING LABORATORY (IPCC)**

**SUBJECT CODE: 21EC33**

**PREPARED BY:**  
**Dr.Prajith Prakash Nair**  
**Associate Professor, ECE**  
**ACS College of Engineering**

# TABLE OF CONTENTS

PRACTICAL COMPONENT OF IPCC		
SL.NO	EXPERIMENT	PAGE NO
1	a. Program to create and modify a vector (array). b. Program to create and modify a matrix.	
2	Programs on basic operations on matrix.	
3	Program to solve system of linear equations	
4	Program for Gram-Schmidt orthogonalization.	
5	Program to find Eigen value and Eigen vector.	
6	Program to find Singular value decomposition.	
7	Program to generate discrete waveforms.	
8	Program to perform basic operation on signals.	
9	Program to perform convolution of two given sequences.	
10	a. Program to perform verification of commutative property of convolution. b. Program to perform verification of distributive property of convolution. c. Program to perform verification of associative property of convolution.	
11	Program to compute step response from the given impulse response.	
12	Programs to find Z-transform and inverse Z-transform of a sequence	

Exp. No. 1 (a): Program to create and modify a vector (Array)

Exp. No. 1 (b): Program to create and modify a Matrix

Aim: To create a vector and perform various operations on it

Apparatus: Matlab Software, PC

Program:

**To create an array with four elements in a single row, separate the elements with either a comma (,) or a space.**

```
a = [1 2 3 4]
```

**To create a matrix that has multiple rows, separate the rows with semicolons.**

```
a = [1 3 5; 2 4 6; 7 8 10]
```

**Another way to create a matrix is to use a function, such as ones, zeros, or rand. For example, create a 5-by-1 column vector of zeros.**

```
z = zeros (5, 1)
```

OUTPUT :

## Exp. No. 2: Programs on basic operations on matrix

Aim: To create a matrix and perform basic operation on it

Apparatus: Matlab Software, PC

Program:

**MATLAB allows you to process all of the values in a matrix using a single arithmetic operator or function.**

`a + 10`

**To transpose a matrix, use a single quote ('):**

`a'`

**You can perform standard matrix multiplication, which computes the inner products between rows and columns, using the \* operator. For example, confirm that a matrix times its inverse returns the identity matrix:**

`p = a*inv(a)`

**To perform element-wise multiplication rather than matrix multiplication, use the .\* operator:**

`p = a.*a`

**The matrix operators for multiplication, division, and power each have a corresponding array operator that operates element-wise. For example, raise each element of a to the third power:**

`a.^3`

***Concatenation* is the process of joining arrays to make larger ones. In fact, you made your first array by concatenating its individual elements. The pair of square brackets [] is the concatenation operator.**

`A = [a,a]`

Concatenating arrays next to one another using commas is called *horizontal* concatenation. Each array must have the same number of rows. Similarly, when the arrays have the same number of columns, you can concatenate *vertically* using semicolons.

$A = [a; a]$

Complex numbers have both real and imaginary parts, where the imaginary unit is the square root of -1.

$\text{sqrt}(-1)$

To represent the imaginary part of complex numbers, use either  $i$  or  $j$ .

$c = [3+4i, 4+3j; -i, 10j]$

OUTPUT

## **Exp. No. 3: Program to solve system of linear equations.**

**Aim:** To create and solve a system of linear equations

**Apparatus:** Matlab Software, PC

**Program:**

If you do not have the system of linear equations in the form  $AX = B$ , use `equationsToMatrix` to convert the equations into this form. Consider the following system.

$$2-x+y-z=3 ; x+2y+3z=-10; x+y+z=2$$

**Declare the system of equations.**

```
syms x y z
eqn1 = 2*x + y + z == 2;
eqn2 = -x + y - z == 3;
eqn3 = x + 2*y + 3*z == -10;
```

**Use `equationsToMatrix` to convert the equations into the form  $AX = B$ . The second input to `equationsToMatrix` specifies the independent variables in the equations.**

```
[A,B] = equationsToMatrix([eqn1, eqn2, eqn3], [x, y, z])
```

**Use `linsolve` to solve  $AX = B$  for the vector of unknowns  $X$ .**

```
X = linsolve(A,B)
```

#### **Exp. No. 4: Program for Gram-Schmidt orthogonalization.**

Aim: To create and solve Gram-Schmidt orthogonalization

Apparatus: Matlab Software, PC

Program:

```
A=[1,2,3;2,3,4;4,5,6];
[m,n]=size(A);
Q=zeros(m,n);
R=zeros(n,n);
For j=1:n
v=A(:,j);
for i=1:j-1
R(i,j)=Q(:,i)'*A(:,j);
v=v-R(i,j)*Q(:,i);
end
R(j,j)=norm(v);
Q(:,j)=v/R(j,j);
end
```

Output:

## Exp. No. 5: Program for Eigen Values and Eigen Vectors.

Aim: To create and solve Eigen values and eigen vector

Apparatus: Matlab Software, PC

Program:

```
A = [-2,-4,2;-2,1,2;4,2,5]
[Eigenvalues_A,Eigenvectors_A] = my_eigen(A)
function [eigenvalues, eigenvectors] = my_eigen(A)
%%This function takes a n by n matrix A and
%%returns the eigenvalues and their associated eigenvectors.
    [m,n] = size(A);
    assert(isequal(m,n), "A is not a square matrix.") %Check to make sure A is a square matrix.
    syms l
    lI = eye(m)*l;
    char_poly = det(A - lI);
    eigenvalues = solve(char_poly,l);
    for i = 1:m %This is to make sure any eigenvalues that = 0 are actually 0.
        if abs(eigenvalues(i)) < 10^-5
            eigenvalues(i) = 0;
        end
    end
    eigenvalues = transpose(eigenvalues); %This makes it easier to know which
                                         %eigenvalue goes with which eigenvector.
    eigenvectors = zeros(m); %This line is to make the code run smoother.
    for i = 1:m
        matrix = A - eye(m)*eigenvalues(i);
        a_eigenvector = null(matrix); %An eigenvector is the nullspace of a matrix minus one of its eigenvalues along the diagonal.
        a_eigenvector = a_eigenvector/min(abs(a_eigenvector)); %This makes the eigenvector look nice and readable.
        eigenvectors(:,i) = a_eigenvector;
```



```
    end  
end
```

**OUTPUT :**

## Exp. No. 6: Program to find Singular value decomposition.

Aim: To perform a program for SVD

Apparatus: Matlab Software, PC

Program :

```
U = Varg;
V = Uarg;
S = Sarg;
A = Aarg';

current_rank = size( U, 2 );
m = U' * A;
p = A - U*m;
P = orth( p );
P = [ P zeros(size(P,1), size(p,2)-size(P,2)) ];
Ra = P' * p;
z = zeros( size(m) );
K = [ S m ; z' Ra ];
[tUp,tSp,tVp] = svds( K, current_rank );
Sp = tSp;
Up = [ U P ] * tUp;
Vp = V * tVp( 1:current_rank, : );
Vp = [ Vp ; tVp( current_rank+1:size(tVp,1), : ) ];
if ( force_orth )
    [UQ,UR] = qr( Up, 0 );
    [VQ,VR] = qr( Vp, 0 );
    [tUp,tSp,tVp] = svds( UR * Sp * VR', current_rank );
    Up = UQ * tUp;
    Vp = VQ * tVp;
    Sp = tSp;
end;

Up1 = Vp;
Vp1 = Up;
```

## Exp. No. 7: Program to generate discrete waveform

Aim: Write a program to generate discrete waveform

Apparatus: Matlab Software, PC

Program :

```
x = rand(100,1) ;  
y0 = rand ;  
n = length(x) ;  
y = zeros(n,1) ;  
y(1) = y0 ;  
for i = 2:n  
    y(i)=y(i-1)+3*x(i) ;  
end  
stem(1:n,y)
```

## **Exp. No. 8: Program to perform basic operation on a signal**

Aim: Write a program to perform basic operation on a signal

Apparatus: Matlab Software, PC

Program :

Addition

```
x=[1 2 3 4];  
subplot(3,1,1);  
stem(x);  
title('X');  
y=[1 1 1 1];  
subplot(3,1,2);  
stem(y);  
title('Y');  
z=x+y;  
subplot(3,1,3);  
stem(z);  
title('Z=X+Y');
```

Subtraction

```
n1=-2:1;  
x=[1 2 3 4];  
subplot(3,1,1);  
stem(n1,x);  
title('X') ;  
axis([-4 4 -5 5]);  
n2=0:3;  
y=[1 1 1 1];  
subplot(3,1,2);  
stem(n2,y);  
title('Y');
```

```

axis([-4 4 -5 5]);
n3 =min (min(n1) ,min( n2 ) ) : max ( max ( n1 ) , max ( n2 ) ); % finding the
duration of output signal
s1 =zeros(1,length (n3) );
s2 =s1;
s1 (find ( ( n3>=min( n1 ) ) & ( n3 <=max ( n1 ) )==1 ) )=x;
% signal x with the duration of output signal 'sub'
s2 (find ( ( n3>=min ( n2 ) ) & ( n3 <=max ( n2 ) )==1 ) )=y;
% signal y with the duration of output signal 'sub'
sub=s1 - s2; % subtraction
subplot(3,1,3)
stem(n3,sub)
title('Z=X-Y');
axis([-4 4 -5 5]);

```

## Multiplication

```

n1=-2:1;
x=[1 2 3 4];
subplot(3,1,1);
stem(n1,x);
title('X') ;
axis([-4 4 -5 5]);
n2=0:3;
y=[1 1 1 1];
subplot(3,1,2);
stem(n2,y);
title('Y');
axis([-4 4 -5 5]);
n3 =min (min(n1) ,min( n2 ) ) : max ( max ( n1 ) , max ( n2 ) ); % finding the
duration of output signal (out)
s1 =zeros(1,length (n3) );
s2 =s1;
s1 (find ( ( n3>=min( n1 ) ) & ( n3 <=max ( n1 ) )==1 ) )=x;
% signal x with the duration of output signal 'mul'
s2 (find ( ( n3>=min ( n2 ) ) & ( n3 <=max ( n2 ) )==1 ) )=y;
% signal y with the duration of output signal 'mul'
mul=s1 .* s2; % multiplication
subplot(3,1,3)

```

```
stem(n3,mul)
title('Z=X*Y');
axis([-4 4 -5 5]);
```

## **Exp. No. 9: Program to perform convolution of two signals**

Aim: Write a program to perform convolution of 2 signals

Apparatus: Matlab Software, PC

### **Program**

```
p=input('Enter the limit for x');
q=input('Enter the limit for y');
x=input('Enter the elements for x');
y=input('Enter the elements for y');
n1=0:p ;
n2=0:q;
subplot(3,1,1);
stem(n1,x);
title('Signal - x(n)');
subplot(3,1,2);
stem(n2,y);
title('Signal - h(n)');
z=conv(x,y);
t=length(n1)+length(n2)-1;
s=0:t-1;
subplot(3,1,3);
stem(s,z);
title('Output - y(n)');
```

## **Exp. No. 10: Program to perform property verification**

Aim: Write a program to perform associative , distributive and commutative property of signals

Apparatus: Matlab Software, PC

Programs



## **Exp. No. 11: Program to perform step response from impulse**

Aim: Write a program to perform step response from impulse

Apparatus: Matlab Software, PC

Programs :

```
load('PulseResponseReflective100ps.mat');  
plot(t,step)  
xlabel('Time (Seconds)')  
ylabel('Volts')  
title('Step Response')
```

## Exp. No. 12: Program to perform Z Transforms and Inverse Z transforms

Aim: Write a program to perform Z Transforms and Inverse Z transforms

Apparatus: Matlab Software, PC

Programs :

Z Transform

```
clc;
close all;
clear all;
syms 'z';
disp('If you input a finite duration sequence x(n), we will give you its z-transform');
nf=input('Please input the initial value of n = ');
nl=input('Please input the final value of n = ');
x= input('Please input the sequence x(n)= ');
syms 'm';
syms 'y';
f(y,m)=(y*(z^(-m)));
disp('Z-transform of the input sequence is displayed below');
k=1;
for n=nf:1:nl
    answer(k)=(f((x(k)),n));
    k=k+1;
end
disp(sum(answer));
```

Inverse Z transform :

```
clc;  
close all;  
clear all;  
syms n;  
syms k;  
syms f(z);  
f(z) = input('Please input a function to obtain its inverse z  
transform ');  
disp(iztrans(f(z)));
```